

TYPICAL MOTOR PERFORMANCE DATA

Model: 0016SDJC41P-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
1	0.75	6	1165	145JP	575	60	3	1.3
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	55	F	1.15	CONT	82.5	B		40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	1.00	0.7	1.3	84.3	67.2
¾ Load	0.75	0.6	1.1	83.1	59.0
½ Load	0.50	0.4	0.9	80.0	50.0
¼ Load	0.25	0.2	0.8	68.8	33.2
No Load			0.8		
Locked Rotor			9.4		

Torque				Rotor wk² Inertia (lb-ft²)
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
4.51	250	180	350	0.18

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
35	15	-	6305ZZC3	6305ZZC3	0

*Bearings are the only recommended spare part(s).

Motor Options:
Mounting:Footed,Shaft:JP Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

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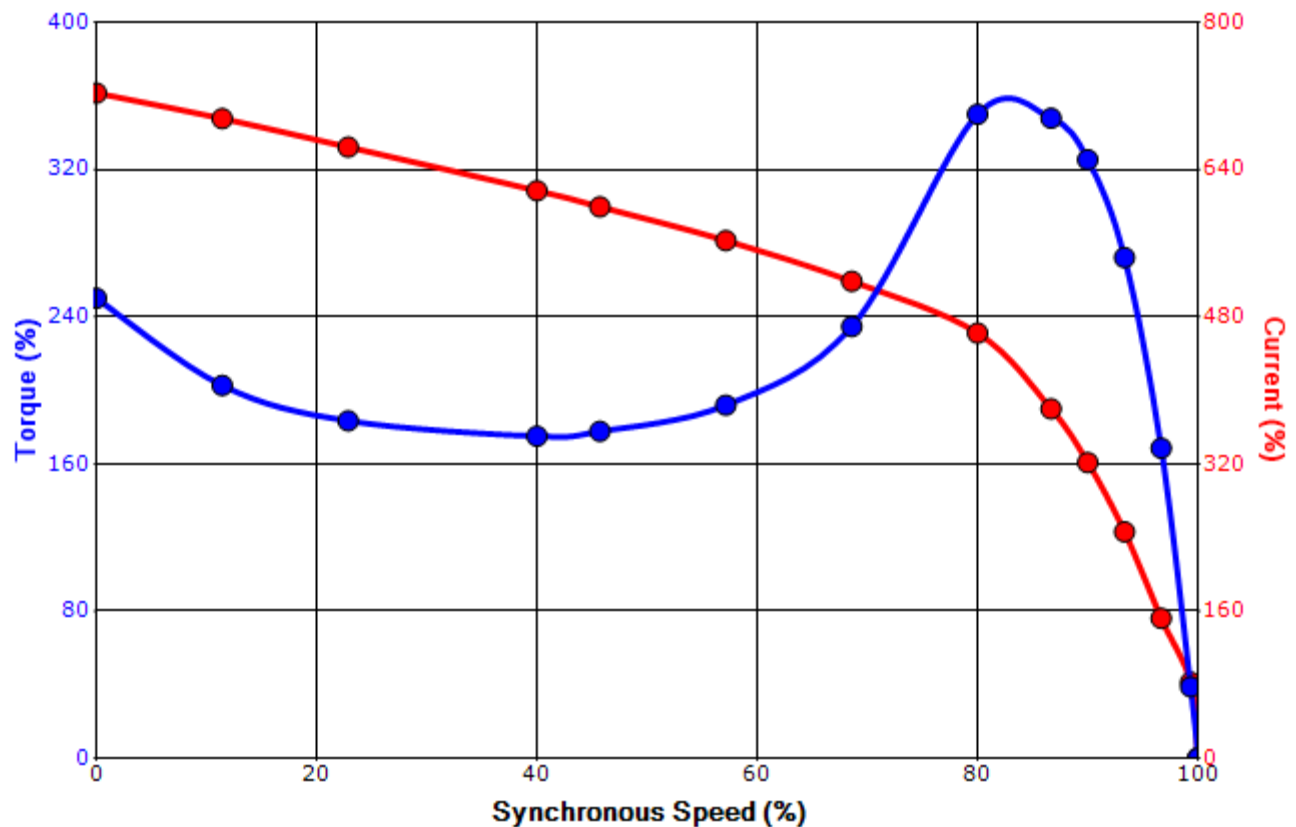
Engineering	spinzon	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	8/5/2024	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: 0016SDJC41P-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
1	0.75	6	1165	145JP	575	60	3	1.3
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	55	F	1.15	CONT	82.5	B		40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)		Break Down (%)		
9.4	0.18	4.51	250	180		350		

Design Values



Customer		wk ² Load Inertia (lb-ft ²)	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

All characteristics are average expected values.

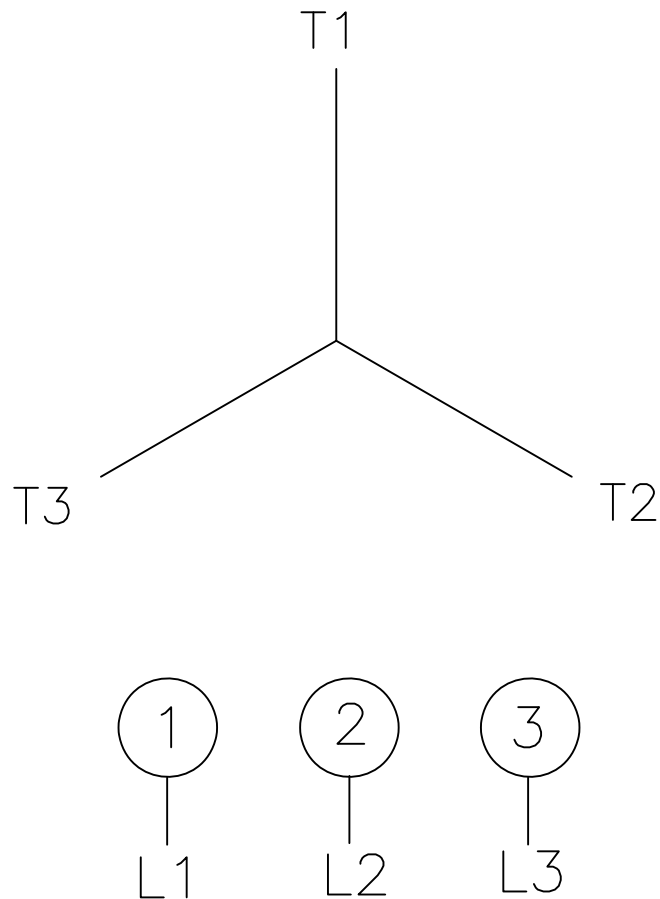
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Motor Connection Diagram

3 Leads - Wye Connection

Single Voltage



Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable.
If multiple cables represent a single lead, each one of them will be labeled with the appropriate lead number.