

UNITS: INCHES

FRAME SIZE	MOTOR DIMENSIONS										CONDUIT BOX					
	A	B	C	D	G	J	K	M	O	P	T	AA	AB	AC	AE	AF
505USS	24.9	20.9	39.0	12.50	1.4	5.6	4.8	17.3	25.6	24.9	4.4	4.00	23.8	18.7	15.7	8.7
505US	24.9	20.9	39.5	12.50	1.4	5.6	4.8	17.3	25.6	24.9	4.4	4.00	23.8	18.7	15.7	8.7
505US	10.00	18.00	0.94	0.94	8.5	4.75	4.50	2.375	2.021	0.625	3.00	6313C3	6313C3	6313C3	2650	lbs.
505US	10.00	18.00	0.94	0.94	8.5	4.75	4.50	2.875	2.450	0.750	3.00	6320C3	6320C3	6320C3	2650	lbs.

- NOTES:
1. DIMENSION V REPRESENTS LENGTH OF STRAIGHT PART OF SHAFT
 2. MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS
 3. KEY DIMENSIONS EQUAL S x S x 3.00 FOR US AND USS (MOTOR SUPPLIED WITH KEY)
 4. MOTOR WEIGHT SHOWN IS MAXIMUM HORSEPOWER IN FRAME
 5. OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE

CUSTOMER: _____ MOTOR MODEL NO.: _____ TAG NO's: _____

P.O. NO.: _____ HP: _____ VOLTAGE: _____ RPM(SYN.): _____ HZ: _____

FRAME SIZE: _____ PRODUCT TYPE: ODP EDP ILL. EPACK. & HIGH EFFICIENCY

COMMENTS: _____

PER: _____ DATE: _____

TOSHIBA RESERVES THE RIGHT TO MAKE CHANGES OF TECHNICAL IMPROVEMENT AND THE DATA MAY CHANGE WITHOUT NOTICE ☒ PRELIMINARY

DO NOT USE FOR CONSTRUCTION, INSTALLATION, OR APPLICATION PURPOSES UNLESS THE DRAWING IS MARKED AS CERTIFIED ☐ CERTIFIED

TOSHIBA OPEN DRIP-PROOF
HORIZONTAL FOOT-MOUNTED
3 PHASE INDUCTION MOTOR
F1 ASSEMBLY

- ☒ STANDARD (NO AUX. BOXES)
- ☐ RTD AUX. BOX
- ☐ SPACE HEATER AUX. BOX
- ☐ BEARING RTD's

XT SERIES

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TYPICAL MOTOR PERFORMANCE DATA

Model: B4002VLG3BMH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
400	298	2	3570	505USS	460	60	3	428
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	22	F	1.15	CONT	95.8	B	G	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	400	298.3	428.0	95.9	91.4
¾ Load	300.00	223.7	324.4	95.5	93.5
½ Load	200.00	149.1	226.2	94.2	87.9
¼ Load	100.00	74.6	137.3	89.7	76.0
No Load			76.0		5.9
Locked Rotor			2900		26.6

Torque				Rotor wk² Inertia (lb-ft²)
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
589	155	145	325	68.27

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
32	15	-	6313C3	6313C3	2341

*Bearings are the only recommended spare part(s).

Motor Options:

Product Family:ODP

Mounting:Footed,Shaft:USS Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

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Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 1
Engr. Date	5/16/2012	Doc. Approved By	M. Campbell	Doc. Issued	9/20/2019

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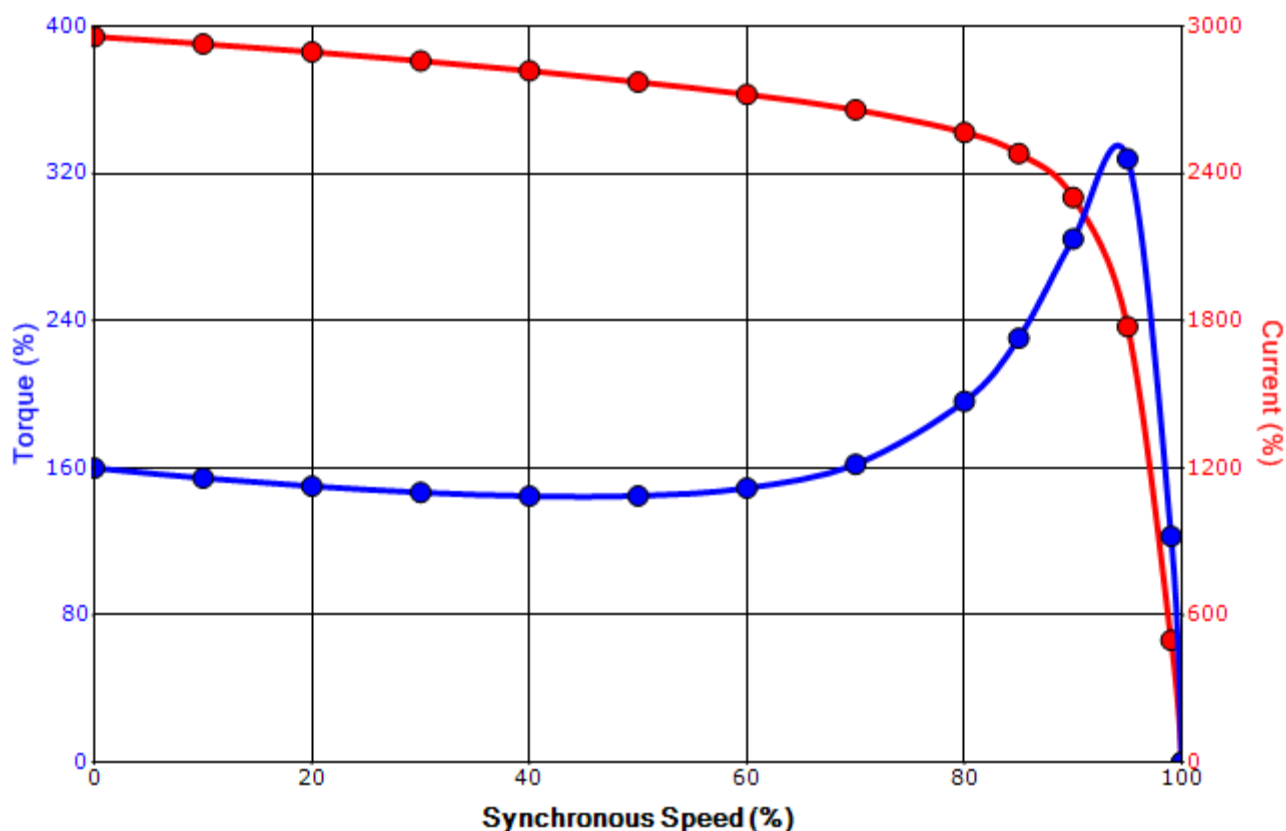
Issued Rev

SPEED TORQUE/CURRENT CURVE

Model: B4002VLG3BMH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
400	298	2	3570	505USS	460	60	3	428
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	22	F	1.15	CONT	95.8	B	G	40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)		Break Down (%)		
2900	68.27	589	155	145		325		

Design Values



Customer		wk ² Load Inertia (lb-ft ²)	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

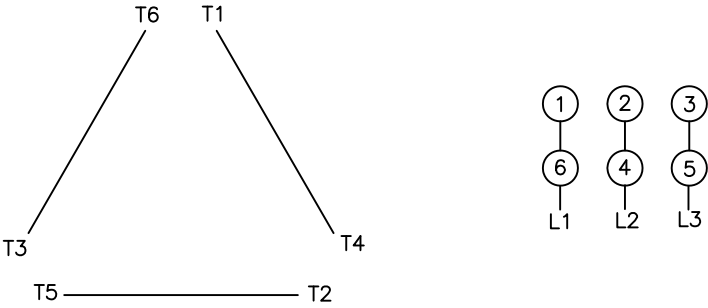
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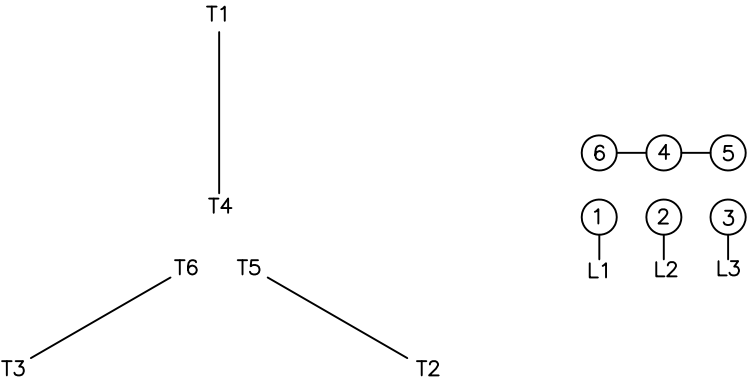
Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121/1
Engr. Date	5/16/2012	Doc. Approved By	M. Campbell	Doc. Issued	9/20/2019

Motor Connection Diagrams
6 Leads

Across the Line Starting / Run - Delta:



Alternate Starting Connection - Wye:



Switch L1 and L2 to reverse rotation