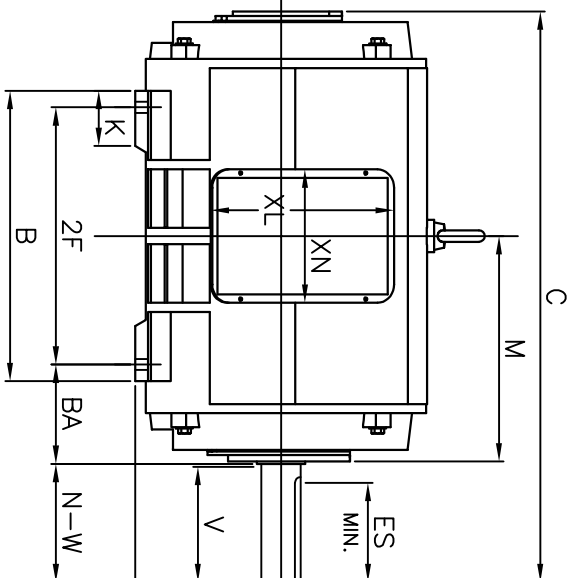
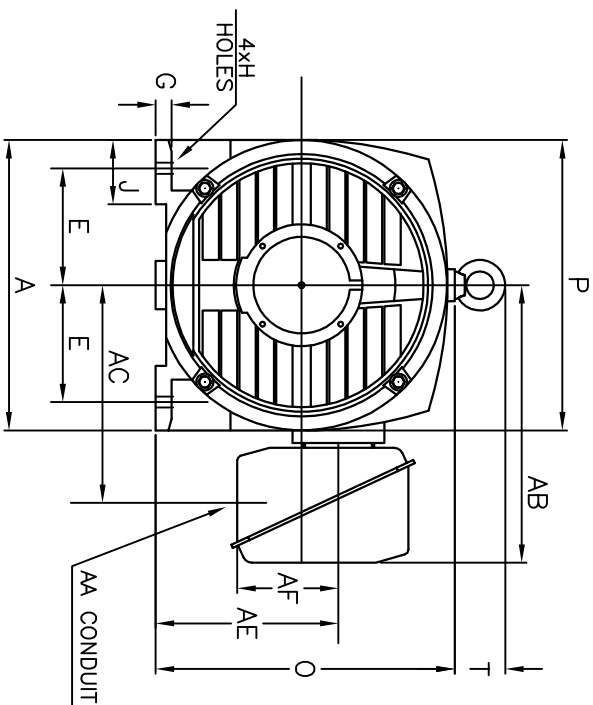
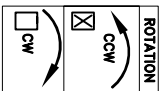


UNITS: INCHES

FRAME SIZE	MOTOR DIMENSIONS											CONDUIT BOX						
	A	B	C	D	G	J	K	M	O	P	T	AA	AB	AC	AE	AF	XL	XN
507USS	24.9	24.9	43.6	12.50	1.4	5.6	4.8	19.3	25.6	24.9	4.4	4.00	23.8	18.7	15.7	8.7	15.7	11.5
507US	24.9	24.9	48.9	12.50	1.4	5.6	4.8	19.3	25.6	24.9	4.4	4.00	23.8	18.7	15.7	8.7	15.7	11.5
FRAME SIZE	MOUNTING				SHAFT EXTENSION				KEY SEAT			BEARINGS			MAXIMUM WEIGHT			
	E	2F	H	BA	N-W	V	U	R	S	ES	LS	OS						
507USS	10.00	22.00	0.94	8.5	4.75	4.50	2.375	2.021	0.625	3.00	6313C3	6313C3	2900 lbs.					
507US	10.00	22.00	0.94	8.5	10.13	9.88	3.375	2.880	0.875	8.50	6320C3	6320C3	2900 lbs.					

CUSTOMER: _____ MOTOR MODEL NO.: _____ TAG NO's.: _____

P.O. NO.: _____ HP: _____ VOLTAGE: _____ RPM(SYN.): _____ Hz: _____
FRAME SIZE: _____ PRODUCT TYPE: ODP EDP III, EPACT, & HIGH EFFICIENCY
COMMENTS: _____

PER: _____ DATE: _____

TOSHIBA RESERVES THE RIGHT TO MAKE CHANGES OF TECHNICAL IMPROVEMENT AND THE DATA MAY CHANGE WITHOUT NOTICE ☒ PRELIMINARY
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TOSHIBA OPEN DRIP-PROOF
HORIZONTAL FOOT-MOUNTED
3 PHASE INDUCTION MOTOR
TOSHIBA INTERNATIONAL CORPORATION F1 ASSEMBLY

☒ STANDARD (NO AUX. BOXES)

☐ RTD AUX. BOX

☐ SPACE HEATER AUX. BOX

☐ BEARING RTD's

- NOTES:
1. DIMENSION V REPRESENTS LENGTH OF STRAIGHT PART OF SHAFT
 2. MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS
 3. KEY DIMENSIONS EQUAL S x S x 8.50 FOR US AND S x S x 3.00 FOR USS (MOTOR SUPPLIED WITH KEY)
 4. MOTOR WEIGHT SHOWN IS MAXIMUM HORSEPOWER IN FRAME
 5. OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE

XT SERIES
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TYPICAL MOTOR PERFORMANCE DATA

Model: B5002VLG3BMH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
500	373	2	3571	507USS	460	60	3	526
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	22	F	1.15	CONT	96.5	B		40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	500.00	372.9	526	96.5	92.4
¾ Load	375.00	279.6	395	96.8	91.8
½ Load	250.00	186.4	274	96.8	89.5
¼ Load	125.00	93.2	163	91.2	78.4
No Load			90.0		5.4
Locked Rotor			3600		21.9

Torque				Rotor wk² Inertia (lb-ft²)
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
735	190	170	360	91.81

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
32	15	-	6313C3	6313C3	1700

*Bearings are the only recommended spare part(s).

Motor Options:
Product Family:ODP
Mounting:Footed,Shaft:USS Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.

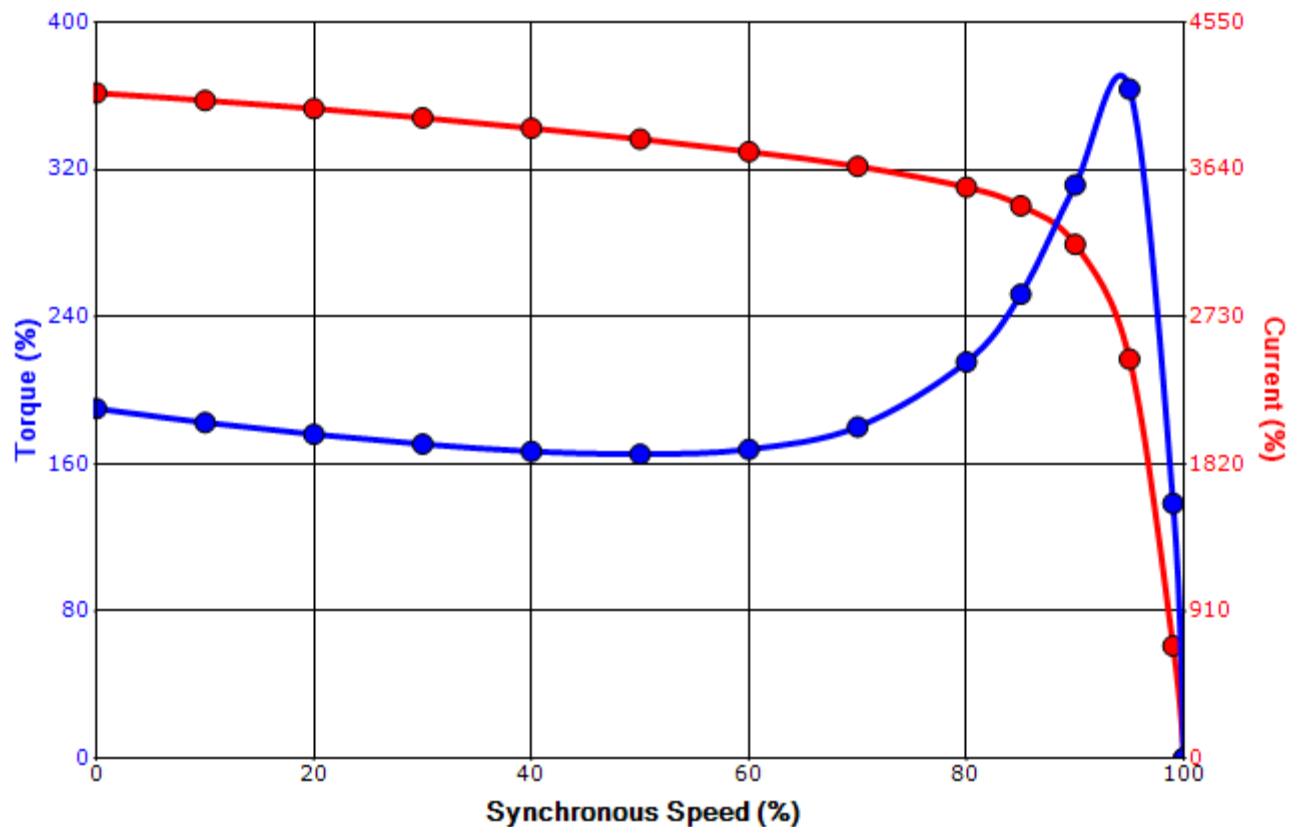
Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	5/16/2012	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: B5002VLG3BMH

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
500	373	2	3571	507USS	460	60	3	526
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
ODP	22	F	1.15	CONT	96.5	B		40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)		Break Down (%)		
3600	91.81	735	190	170		360		

Design Values



Customer		wk ² Load Inertia (lb-ft ²)	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.

Engineering	aacosta	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
Engr. Date	5/16/2012	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

Motor Connection Diagram

12 Leads

Single Voltage



Switch L1 and L2 to reverse rotation